

[H5.応4]  $\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 0 & -5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u$   $y = \begin{bmatrix} k & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$

(1)  $\dot{x}_1 = -x_2 \rightarrow sX_1(s) = X_2(s)$   
 $\dot{x}_2 = -5x_2 + u \rightarrow sX_2(s) = -5X_2(s) + U(s)$   
 $y = kx_1 \rightarrow Y(s) = kX_1(s)$

状態方程式の各要素をラプラス変換可能。(微分方程式)

$s^2 X_1(s) = -5sX_1(s) + U(s)$

$X_1(s) = \frac{U(s)}{s^2 + 5s}$

$Y(s) = \frac{kU(s)}{s^2 + 5s}$

前路伝達関数  $G(s) = \frac{Y(s)}{U(s)} = \frac{k}{s^2 + 5s}$

$u \cdot G = y$

$W(s) = \frac{Y(s)}{R(s)} = \frac{G(s)}{1 + G(s)} = \frac{\frac{k}{s^2 + 5s}}{1 + \frac{k}{s^2 + 5s}} = \frac{k}{s^2 + 5s + k}$

(2) 2次系標準形

$W(s) = \frac{\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2}$  と比較して、 $2\zeta\omega_n = 5$ ,  $\omega_n^2 = k$ ,  $\zeta = 0.4$  (題意)

$\omega_n = \frac{5}{0.8} = 6.25$

$k = 6.25^2 = 39.0625 \approx 39.1$

題意より  $k = 6 \text{ である}$

(3)  $W(s) = \frac{6}{s^2 + 5s + 6}$

ステップ応答 (a) のラプラス変換と (b) の計算:

$C(s) = W(s)U(s) = \frac{6}{s^2 + 5s + 6} \cdot \frac{1}{s} = \frac{6}{s(s+2)(s+3)} = \frac{A}{s} + \frac{B}{s+2} + \frac{C}{s+3}$

$= \frac{1}{s} - \frac{3}{s+2} + \frac{2}{s+3}$

$A = \frac{6s}{s(s+2)(s+3)} \Big|_{s=0} = \frac{6}{6} = 1$

$B = \frac{6(s+2)}{s(s+2)(s+3)} \Big|_{s=-2} = \frac{6}{-2} = -3$

$C = \frac{6(s+3)}{s(s+2)(s+3)} \Big|_{s=-3} = \frac{6}{3} = 2$

$c(t) = \mathcal{L}^{-1}\{C(s)\} = 1 - 3e^{-2t} + 2e^{-3t}$